

# Genetic Algorithms

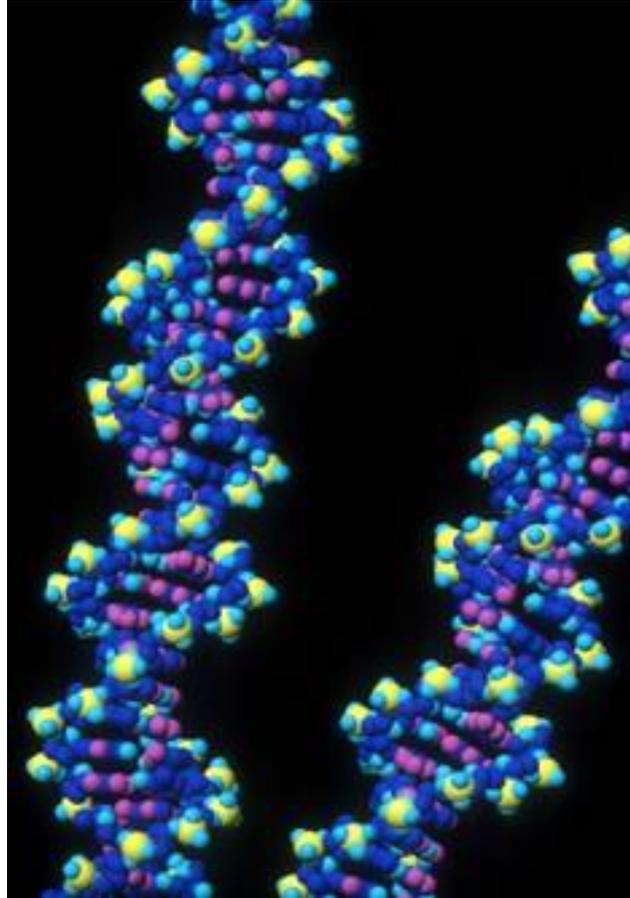
→ because it sounds cool!

Probably the **Most Popular** Heuristic Algorithm  
*(but not necessarily the best for some applications)*

Handout 9-9-11

# Genetics and Genetic Algorithms

*Nucleic*  
~~Nucleic~~ acids  
carrying  
genetic  
information



We are all interested in our own genetics so perhaps that is one of the reasons Genetic Algorithms are so popular.

# Genetic Algorithms

- The heuristic search method Genetic Algorithms is **inspired by** the mechanism Nature uses to “improve” populations. *→ much the way Simulated Annealing is inspired by the annealing process in materials science*
- Among animals, each parent has **genes**.
- The genes of a child are directly related to the genes of the parents.
- The ability of an organism to survive (fitness) depends directly on the child’s genes.
- In the algorithm analogy, **“genes” are decision variables**.

# Effect of Genetic Alteration



Plant on the left is unaltered and the right has been genetically altered so the plants have different genes. *actually the implementation of the genes are different.*

Both plants are the same age. Algorithm analogy is that right side is a “good” solution and left side is a “bad” solution.

# Population Genetics Suggests Heuristic

- “Survival of the fittest” means that children whose genes give high fitness are more likely to survive and produce more children.
- In this way over time, **genes** with characteristics **beneficial** for survival appear in an increasing fraction of the population and hence **“fitness”** of the population improves.
- It is an analogy of this principle that is the basis for the heuristic called “Genetic Algorithm”.

# Definition

- Gene- basic genetic element
- Chromosome- a collection of genes *← or set of genes*
- Allele- The values a gene can take (e.g. we usually have alleles = 0 or 1).
- Examples: Let  $S$  be a binary string of length 4 so
  - Chromosome example are 1010, 0110, etc.
  - Genes are the bits in the string *→ we assume genes are only 1-bit, but they could be more.*
  - Alleles are 0 or 1 *0-3 allele ⇒ 2-bit gene, etc*
- For most heuristic optimization cases one chromosome = “genotype” = “phenotype”
  - (The actual biological distinction is more complex.)
- ”

## Definitions (continued)

- For genetic algorithms, the objective function is called “Fitness” which we will call  $F(S)$  (not  $\text{Cost}(S)$ ).
- We want to maximize the fitness  $F(S)$   
*↳ if you have a minimization problem, flip the sign of the output of the cost function*
- An iteration of the GA algorithm is called a “generation”

# Biggest Difference Between Genetic Algorithm and SA

- Simulated annealing carries the single “curS” from one iteration to the next.

↳ current S

- Genetic algorithms carry many solutions from one iteration to the next.

- These many solutions are called a “population”

- You can think of a population as a vector of current S's.
- This allows you to carry many solutions to improve robustness of the algorithm.

# Introduction to Genetic Algorithms (cont.)

- **The primary operations in Genetic Algorithms are**
- **Crossover** (this involves switching locations of substrings within a binary string) *⇒ swapping genes with other solutions*
- **Mutation** (this involves changing the value of one value (e.g. one gene) in the binary string based on a probability distribution) *⇒ forced permutation to explore the search space*

# Characteristics of Genetic Algorithms

(GA) :

- They require an effective representation of the decision variables in the form of a **chromosome** (encoded **string**). For “binary coded GA”, this is a string of 0’s and 1’s.
- In each iteration (generation) there are **multiple members of population** ( $CurSi, I=1, \dots, M$ )
- The method is stochastic (i.e. they search using probabilistic functions)
- The method does not know **when to stop**. Usually set maxtime.

## Characteristics of Genetic Algorithms (continued)

- (Like other heuristics) the algorithm only requires the **objective function value (S)**. (It doesn't require derivatives, continuity, etc.)  
*→ essentially the cost(Cs) we are used to, also called F(Cs)*
- However, knowledge of problem structure can possibly be incorporated into the encoding of the string or into the reproductive process to improve performance.  
*→ string structure can affect outcome due to mutation and crossover*
- Initially we will discuss decision variables that are **binary strings** (e.g. 0110010) for GA

# Basic structure of genetic algorithms

- 1. Randomly generate an initial “population”. ( $\text{CurS}_j$ ) for all  $j= 1, \dots, M$ .
- 2. Compute  $F(\text{CurS}_j)$  for all  $j= 1, \dots, M$ . (Objective Function)  $O(n \cdot \text{population} \cdot O(\text{cost function}))$   
*(Handwritten note:  $n$  is population,  $O(\text{cost function})$  is iterations)*
- 3. Generate “children” which are the members of the population in the next generation. This is done by applying **crossover** and **mutation**, which are influenced by the values of the  $F(\text{CurS}_j)$ . Every child has two parents.
- 4. The population of children becomes a population of parents and go to step 2 unless a stopping criterion has been satisfied.

# Crossover (Roulette)

- In order to generate N children you will perform the following:
  - Randomly **select** one parent with a probability that is **proportional to its fitness**  $F(S_i)$ .  
*→ selection of the fittest parents*
  - Then randomly **select** a second parent also with a probability that is **proportional to the fitness** of the parent.
  - For one point crossover: **pick a crossover point**. This can be done **randomly** although there may be some restrictions discussed later.  
*→ usually uniform random*
  - Then switch the portions of the binary strings that occur before the crossover point between the parents.

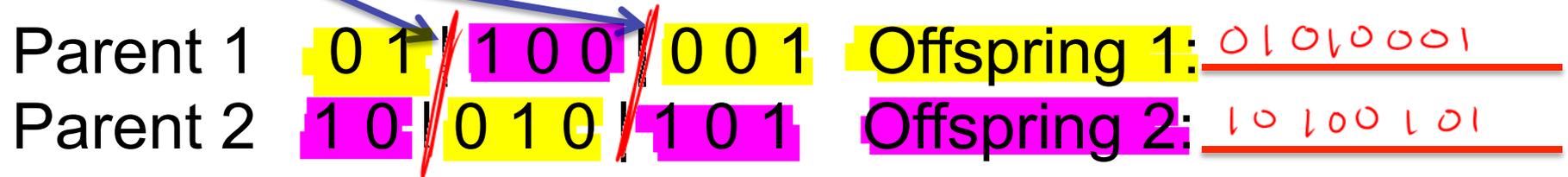
# Generating Children with *Crossover*

- The simple <sup>one-point</sup> cross over procedure is
  - Parent 1    0 1 1 0 0 | 0 0 1    Offspring 1: 0 1 1 0 0 | 1 0 1
  - Parent 2    1 0 0 1 0 | 1 0 1    Offspring 2: 1 0 0 1 0 | 0 0 1
- one-point*
- crossover point*

Note: in some cases you may choose to have only one offspring.

# Multipoint Crossover

Another method for binary strings is Multipoint Crossover



Where multiple crossover points are randomly generated. (Two crossover points are in the example above.)

*⇒ we'd want to put related things next to each other to capture correlation in this binary string*

*⇒ note you could generate more children here, but we are assuming we don't*  
*⇒ really this is just another way of representing the statement "swap a specific subset of bits"*

# Mutation

- Mutation produces incremental random changes in the offspring by randomly changing allele values. Typically a mutation “flips” a value (e.g. 0 to 1) when S is a binary string. *↳ chosen at random, usually uniform probability*
- Mutation produces new characteristics.
- Without mutation, there can be some values you can never reach.

*⇒ This helps you explore the search space*

~~Maximize  $F(S) = S^3 - 60S^2 + 900S + 100$~~

(Same problem solved with Simulated Annealing.)

$$F(s) = s^3 - 60s^2 + 900s + 100$$

- S is a scalar integer represented in binary form
- The decision vector is a binary string with 5 elements.
- The total number of times the objective function is evaluated is 10 (same as for SA example)
- Table 1.12 (next slide) is initial population, which is 5 randomly generated strings) (note P(select) is proportional to fitness F(x))

# Basic structure of genetic algorithms (Repeated Slide)

- 1. Randomly generate an initial “**population**”.  
(CurS<sub>j</sub>) for all j= 1, ..., M. *M=5 initially*
- 2. Compute **fitness** F(CurS<sub>j</sub>) for all j= 1, ..., M.  
(Objective Function)
- 3. Generate “children” which are the members of the population in the next generation. This is done by applying **crossover** and **mutation**, which are influenced by the values of the F(CurS<sub>j</sub>). Every child has two parents.
- 4. The population of children becomes a population of parents and go to step 2 unless a stopping criterion has been satisfied.

- In the next slide there is a probability of selection of a parent.
- We will discuss later how this probability is selected.

# Initial Population of N=5

Table 1.12 Five random strings

No.	<i>Randomly Generated</i> String	<i>fitness</i> $x$	$f(x)$	<i>Probability of Selection</i> $P[\text{select}]$
1	10011	19	2399	0.206
2	00101	5	3225	0.277
3	11010	26	516	0.044
4	10101	21	1801	0.155
5	01110	14	3684	0.317
Average fitness			2325	

Selection of Parents and Crossover and Mutation positions (Assumes selection based on probability weighted selection. Weight for parents depends on their fitness.

*from table 1.12*

*← crossover point 4*

- Parent 1: 10011
- Parent 2: 00101
- Crossover point 4  $\Rightarrow$  *no difference between #5.*
- Mutation position 4

# All 5 Children (Offspring) created after first iteration (generation) with Population of 5

Table 1.13 A typical experiment.

*take only the first child*

*fitness*

Step	Parent 1	Parent 2	Crossover point	Mutation?	Offspring String	$f(x)$
1	1	2	4	NNN <b>Y</b> N	10001	2973
2	5	3	2	NNNNN	01010	<b>4100</b>
3	5	2	3	NNNNN	01101	3857
4	4	2	1	<b>N</b> YNNN	11101	129
5	2	5	4	NNNNN	00100	2804
Average fitness						2773

*converged very quickly*

How did this do in comparison to Simulated Annealing? Would you expect GA to work this well in general with few evaluations of  $f(x)$ ?

Maximize Cost (S) =  $S^3 - 60 S^2 + 900 S + 100$ .

S is a scalar integer represented in binary form

Initial temperature is 500,  $S_0=1011$ , Cost ( $S_0$ )=2399

## Review: Simulated Annealing Approach to Same Problem

Table 1.5 Second Attempt: T=500

T	Changed bit	S <sub>new</sub> string	J(S <sub>new</sub> )	delta Δf	accept move?	S <sub>0</sub> new string	J(S <sub>0</sub> )
500	1	00011	2287	112	Y	00011	2287
450	3	00111	3803	< 0	Y	00111	3803
405	5	00110	3556	247	Y	00110	3556
364.5	2	01110	3684	< 0	Y	01110	3684
328.0	4	01100	3988	< 0	Y	01100	3988
295.2	3	01000	3972	16	Y	01000	3972
265.7	4	01010	4100	< 0	Y	01010	4100
239.1	5	01011	4071	29	Y	01011	4071
215.2	1	11011	343	3728	N	01011	343

optimal 4100

from Simulated Annealing  
handout with with 7 evaluations

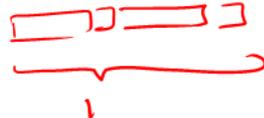
# Selection Methods Picking Parents for Crossover

- The method used in the previous table is **Roulette**. Compute the  $p_i$ , the probability of parent  $S_i$  being selected is

$P[\text{select}] =$  probability of an individual  $i$  being selected as a parent.  $P[\text{select for } S_i] = P_i$

$$P_i = \frac{F(S_i)}{\sum_{j=1}^N F(S_j)} \Rightarrow \sum_{j=1}^N P_j = 1$$

uniform random, pick a place,  
choose that parent



# All Children (Offspring) created after first iteration (generation) (Repeated Slide)

Table 1.13 A typical experiment.

Step	Parent	Parent	Crossover point	Mutation?	Offspring	
	1	2			String	$f(x)$
1	1	2	4	NNNYN	10001	2973
2	5	3	2	NNNNN	01010	4100
3	5	2	3	NNNNN	01101	3857
4	4	2	1	NYNNN	11101	129
5	2	5	4	NNNNN	00100	2804
Average fitness						2773

In this example, parents are picked at random by “Roulette” method.

## Alternative Method for Crossover is **Tournament** Selection

- 1. Let all parents have an equal probability of being selected (e.g.  $p_i = 1/M$ , where  $M$  is number of individuals in the population).
- 2. Pick two parents  $S_i$  and  $S_k$  at random.
- 3. Select the parent with the higher fitness to be the first parent.
- 4. Repeat the process starting with step 1 to select the second parent (if 2 offspring/parent)

Next you select a crossover point and mutation to generate the new child.

Closer to the way parents are selected for some species. 26